# On Using Graph Signal Processing for Electrical Load Disaggregation

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# Outline

- Electrical Load Disaggregation Motivation
- Problem Formulation
- Introduction to graph signal processing
- Proposed solution using Graph Signal Processing (GSP)
- Experimental Results
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# Electrical Load Disaggregation-Motivation

- Electrical Load Disaggregation/ Non-Intrusive Load Monitoring: an instance of Source Separation Problem
- Disaggregate overall household energy consumption into load level without using any devices/ plugs to capture consumption data from individual loads



 Knowledge about the energy consumption of individual loads is key in demand energy optimization.

## **Problem Formulation**

- **Problem:** Given the aggregate power measurement X(t), it is required to compute the contribution of individual loads  $X_m(t)$  which could have resulted in that measurement
- The aggregate power can be expressed as:

$$\boldsymbol{X}(t) = \sum_{m=1}^{M} \boldsymbol{X}_{m}(t) + \boldsymbol{\eta}$$

- Here  $m \in M$ ,, where M is the total number of loads of interest and  $\eta$  is the measurement noise at time instant t
- Objective: Load identification and consumption estimation
- One recent attempt is to use Graph Signal Processing (GSP) to solve it

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# Graphs

Online social media







Image-graph



functional connectivity between brain regions

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 $^{1}$ Google images

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#### Introduction to Graphs and examples

- Formally, a graph G (or a network) is a triplet  $(\mathcal{V}, \mathcal{E}, W)$ .
- Unweighted and directed graphs
- $\mathcal{V} = \{1, 2, \dots, N\}$
- $\mathcal{E} = \{(0,1), \dots, (22,23), (23,0)\}$
- $W:(n,m) \to 1;$  for all  $(n,m) \in \mathcal{E}$





• Unweighted and undirected graphs

• 
$$\mathcal{V} = \{1, 2, \dots, N\}$$

- $\mathcal{E} = \{\{1, 2\}, \{2, 3\}, \dots, \\ \{8, 9\}, \{1, 4\}, \dots, \{6, 9\}\}$
- $\bullet \ W: (n,m) \to 1; \, \text{for all} \, \, (n,m) \in \mathcal{E}$

# Graph signals

- Graph signals are mappings  $x: V \to R$
- Defined on the vertices of the graph
- May be represented as a vector  $x \in \mathbb{R}^N$
- $x_n$  represents the signal value at the nth vertex in V
- Inherently utilizes an ordering of vertices



same ordering as in adjacency matrices

#### Adjacency matrices

- Given a graph  $G = (\mathcal{V}, \mathcal{E}, W)$  of N vertices,
- Its adjacency matrix  $\mathbf{A} \in \mathbb{R}^{N imes N}$  is defined as

$$A_{nm} = \begin{cases} w_{nm}, & \text{ if}(\mathsf{n}, \mathsf{m}) \in \mathcal{E} \\ 0, & \text{ otherwise} \end{cases}$$

- $\bullet$  A matrix representation incorporating all information about  ${\cal G}$ 
  - For unweighted graphs, one represent connected pairs
- Inherently defines an ordering of vertices



#### Degree matrix

- The degree matrix  $D \in \mathbb{R}^{N \times N}$  is a diagonal matrix s.t.  $D_{ii} = \text{deg}(i)$
- Given a weighted and undirected graph  $G = (\mathcal{V}, \mathcal{E}, W)$ .
- The degree of a node is the sum of the weights of its incident edges
- Equivalently, in terms of the adjacency matrix A

• 
$$\operatorname{deg}(i) = \sum_{j} A_{ij} = \sum_{j} A_{ji}$$



#### Laplacian of a graph

- Given a graph G with adjacency matrix A and degree matrix D
- We define the Laplacian matrix  $\mathcal{L} \in \mathbb{R}^{N imes N}$  as

 $\mathcal{L} = D - A$ 

 $\mathcal{L} = Laplacian matrix$ 



• The normalized Laplacian can be obtained as  $\mathcal{L} = D^{-1/2} \mathcal{L} D^{-1/2}$ 

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#### Laplacian quadratic form

• We can also define the Laplacian quadratic form of x

$$s^{\top} \mathcal{L} s = \frac{1}{2} \sum_{j \in \mathcal{N}_i} w_{ij} (s_i - s_j)^2$$

- $s^{\top} \mathcal{L} s \geq 0$  for  $s \neq 0, \mathcal{L}$  is positive semi-definite
- Total variation of a signal is defined as the sum of squared differences in consecutive signalsamples  $\sum_n (s_n s_{n-1})^2$

$$TV_{\mathcal{G}}(s) = \sum_{i=1}^{N} \sum_{j \in \mathcal{N}_i} w_{ij} (s_i - s_j)^2 = s^{\top} \mathcal{L}s$$

• A constant vector 1 is an eigenvector of  $\mathcal L$  with eigenvalue 0

$$\mathbf{1}^{\top} \mathcal{L} \mathbf{1} = \frac{1}{2} \sum_{j \in \mathcal{N}_i} w_{ij} (1-1)^2$$

#### GSP Based Load Disaggregation

• Load disaggregation can be formulated as t optimization problem:

$$\min_{\mathbf{X}_m} \beta \left\| \mathbf{X} - \sum_{m=1}^M \mathbf{X}_m \right\|_2^2 + \alpha \sum_{m=1}^M Tr(\mathbf{X}_m^T \mathbf{L}_m \mathbf{X}_m)$$
(1)

- The above minimization problem in (1) is NP hard especially when number of loads M and time instants N are large
- Proposed Method: Graph Laplacian based regularization approach.
  - Embed the structure of the X(t) on to a graph  $G = (\mathcal{V}, \mathcal{E}, W)$
  - ▶ Represent the  $\mathbf{X}_m(t)$  as a signal S on the graph  $\mathcal{G}$
- Assumption: Graph signal is piecewise smooth graph total variation is small

Graph Total Variation is given by:  $s^{\top} \mathcal{L} s = \frac{1}{2} \sum_{j \in \mathcal{N}_i} w_{ij} (s_i - s_j)^2$ 

where, s is the graph signal and  $\mathcal{L}$  is the graph Laplacian

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- For a N length vector of aggregate data x, i = 1, ..., N, suppose the individual load power data is known for n samples  $(i \le n < N)$
- The graph signal associated with the individual load power measurements  $X_m$  has two parts corresponding to train and test and is given as  $X_m(1:n) = X_m^{train}$  and  $X_m(n+1:N) = X_m^{test}$ . The load signal is represented as  $X_m = [X_m^{train} | X_m^{test}]$ .
- the load signal in the test phase  $X_m^{test}$  is estimated by re-formulating the optimization problem in (1) as:

$$\min_{\boldsymbol{X}_{m}^{test}} \beta \left\| \boldsymbol{X}^{test} - \boldsymbol{X}_{m}^{test} \right\|_{2}^{2} + \alpha Tr(\boldsymbol{X}_{m}^{T} \boldsymbol{L}_{m} \boldsymbol{X}_{m})$$
(2)

problem with a closed form solution:

$$\boldsymbol{X}_{m}^{test} = (\beta I(n+1:N,n+1:N) + \alpha \boldsymbol{L}_{m}(n+1:N,n+1:N))^{-1}.$$
$$(\beta \boldsymbol{X}^{test} - \alpha \boldsymbol{L}_{m}(n+1:N,1:n) \boldsymbol{X}_{m}^{train}) \quad (3)$$

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#### Algorithm 1 Electrical Load Disaggregation using GSP

- Input: aggregate power X, individual loads powers  $X_m(i)$  where  $1 \le i \le n$ ,  $\alpha = 0.9$  and  $\beta = 0.1$
- Set m = 1 (Consider one load at a time)
- $\textcircled{O} \quad \text{While } m \leq M \text{ do}$
- **③** Construct a graph  ${m G}_m$  using  ${m W}_m$  from using Gaussian kernel based on X
- **(**) Compute  $D_m$  and  $L_m$  from  $W_m$  using definitions.
- Evaluate  $X_m^{test}$  using (3)
- **O** Modify the aggregate by setting  $X = X [X_m^{train} | X_m^{test}]$
- **(**) Modify the test aggregate by setting  $m{X}^{test} = m{X}^{test} m{X}^{test}_m$

$$9 \ {\rm Set} \ m = m+1$$

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# Disaggregation Results - REDD 1 Min sampled Data



Disaggregation Results for Kitchen outlets with 1 minute Data



Disaggregation Results for all loads with 1 minute Data

## Disaggregation Results - REDD 15Mins sampled Data



Disaggregation Results for Dryer with 15 minutes Data

#### Performance Analysis

#### Results Summary with 1 minute sampled REDD

Performance Analysis			
Load	F-score	% Acc	
Geyser	0.98	98	
Kitchen	0.94	94	
Refrigerator	0.96	97	
Lighting	0.92	96	

#### Results Summary with 15 minutes sampled REDD

Performance Analysis			
Load	F-score	% Acc	
Dryer	1	90.5076	
Dishwasher	0.888	82.93	
Geyser	0.81899	88.056	
Lighting	0.9083	79.7326	

# Conclusion

- Graph signal processing based algorithm.
  - Formal Data-driven approach,
  - Robust,
  - Scalable and flexible,
  - Low-complexity, even with a large amount of data
- GSP based methods outperform the conventional methods for load disaggregation
- Future direction of electrical load disaggregation is graph is learned based on total aggregate power measurement.

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